Applicant : Jeffrey L. Elkins

Appln. No. :

10/585,978

Page

In the Claims:

This listing of claims will replace all prior versions and listings of claims in the application:

(Currently Amended) A foot-operated controller comprising:

a substrate having a plurality of pressure sensors mounted at selected locations on the substrate to facilitate control of a controllable device by application of pressure from selected parts of a foot to the sensors; and

a microprocessor for receiving input from the sensors and converting the sensor inputs into commands for the controllable electromechanical device.

- (Currently Amended) The foot-operated controller of claim 1, further comprising a 2. radio transmitter for senverting pressure exerted on the sensors by various parts of a foot into control signals that are broadcast to a receiver and transmitted to an electromechanical an sending the commands to the controllable device.
- (Original) The foot-operated controller of claim 1, located on or within the insole of a 3. shoe.
- (Currently Amended) The foot-operated controller of claim 1, in which the microprocessor is hard-wired to the controllable electromechanical device.
- (Original) The foot-operated controller of claim 1, wherein the microprocessor is 5. located on the substrate.

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Page

- (Currently Amended) A prosthetic system comprising: 6.
 - a controllable prosthetic device;
- a foot-operated controller including a substrate having a plurality of pressure sensors mounted at selected locations on the substrate to facilitate control of the controllable prosthetic device; and
- a microprocessor for receiving input from the sensors and converting the sensor inputs into commands for the controllable prosthetic device.
- (Original) The prosthetic system of claim 6, wherein the prosthetic device is a 7. prosthetic hand.
- (Currently Amended) The prosthetic system of claim 6, further comprising a radio transmitter for converting pressure exerted on the sensors by various parts of a foot into control signals that are broadcast to a receiver and transmitted to an electromechanical an sending the commands to the controllable prosthetic device.
- (Original) The prosthetic system of claim 6, located on or within the insole of a shoe. Q
- (Currently Amended) The prosthetic system of claim 6, in which the microprocessor is 10. hard-wired to the controllable electromechanical device.
- (Original) The prosthetic system of claim 6, wherein the microprocessor is located on 11. the substrate
- (New) The foot-operated controller of claim 1 further comprising a controllable 12. prosthetic device operatively connected to the microprocessor to provide commands to the controllable prosthetic device in response to input from the sensors of the foot-operated controller.